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**Dynamic Study Of Laminated Composite Plate** 

**PRESENTATION PLAN** 

## INTRODUCTION

FORMULATION OF THE (R4FSDT) BASED ON THE FIRST ORDER SHEAR DEFORMATION THEORY

VALIDATION TESTS OF THE R4FSDT ELEMENT

**CONCLUSION AND PERSPECTIVES** 



#### **Engineering applications « composite materials »**









# Introduction Formulation of (R4FSDT) Validation Tests Conclusion and perspectives





The development of modern technologies requires the use of materials with high mechanical properties specific to their use, but with low densities.



Among these materials the laminated composite plates which are the most used in engineering industry.



#### Figure. 7 Laminated composite materials.



For the efficient use of this type of material, it is necessary to know their structural and dynamic behaviour as well as have a precise understanding of the stress distribution and natural frequencies.





There are several theories for the study of the multilayer structures behaviour, among which we can cite :

#### Classical Lamination Plate Theory (CLPT)

First order Shear Deformation Theory (FSDT)

Higher order Shear Deformation Theory (HSDT)



Figure. 8 Illustration of Deformation of Classical Lamination Plate Theory

the  
displacements 
$$U = \begin{cases} u(x, y) \\ v(x, y) \\ w(x, y) \end{cases} = \begin{cases} u_0(x, y) - z \frac{\partial w_0(x, y)}{\partial x} \\ v_0(x, y) - z \frac{\partial w_0(x, y)}{\partial y} \\ w_0(x, y) \end{cases}$$



**Eric Reissner (1913-1996)** 

Raymond David Mindlin (1906-1987)

Figure. 9 Mindlin theory assumption for the shell element.

$$\begin{cases} u(x, y, z, t) \\ v(x, y, z, t) \\ w(x, y, z, t) \end{cases} = \begin{cases} u_0(x, y, t) + z \varphi_x(x, y, t) \\ v_0(x, y, t) + z \varphi_y(x, y, t) \\ w_0(x, y, t) \end{cases}$$



Figure. 10 Undeformed and deformed geometries of an edge of a plate in various plate theories.



# FORMULATION OF RECTANGULAR PLATE ELEMENT BASED ON THE FIRST ORDER SHEAR DEFORMATION THEORY (R4FSDT)

## **STATIC ANALYSIS**





Evaluation of the Element Stiffness Matrix :

The total potential energy of plate deformation subjected to transverse loading distributed across its surface is given by:

$$\Pi = U + W$$

#### Potential energy of deformation is given by :

$$U = \frac{1}{2} \int_{v} \sigma \quad \varepsilon^{T} \, dv$$
$$U = \frac{1}{2} \int_{A} \left( \{\varepsilon_{m}\}^{T} \{N\} + \{k\}^{T} \{M\} + \{\gamma\}^{T} \{Q\} \right) dA$$
$$U = \frac{1}{2} \{q\}^{T} \int_{A} \left( \{B_{m}\}^{T} [A] \{B_{m}\} + \{B_{m}\}^{T} [B] \{B_{f}\} + \{B_{f}\}^{T} [B] \{B_{m}\} + \{B_{m}\}^{T} [B] \{B_{m}\} + \{B_{f}\}^{T} [B] \{B_{f}\} + \{B_{f}\}^{T} [B] \{B_{m}\} + \{B_{f}\}^{T} [B] \{B_{m}\} + \{B_{f}\}^{T} [B] \{B_{f}\} + \{B_{f}\}^{T} [B] \{B_{m}\} + \{B_{m}\}^{T} [B] \{B_{m}\} + \{B_{m}\}^{T}$$

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### The equilibrium configuration :

The equilibrium configuration is defined by the minimization of the total potential energy which means the cancellation of its first variation, namely:

$$\partial \Pi = \delta U - \delta W = 0$$

$$\int_{A} \left[\left\{\partial q\right\}^{T} \left(\left\{B_{m}\right\}^{T} \left[A\right]\left\{B_{m}\right\} + \left\{B_{m}\right\}^{T} \left[B\right]\left\{B_{f}\right\} + \left\{B_{f}\right\}^{T} \left[B\right]\left\{B_{m}\right\} + \left\{B_{f}\right\}^{T} \left[D\right]\left\{B_{f}\right\} + \left\{B_{c}\right\}^{T} \left[H\right]\left\{B_{c}\right\}\right] dA - \left\{\partial q\right\}\left\{F^{e}\right\} = 0$$

The assembly of element stiffness matrices and forces vectors leads to the following equation:

$$[K]{q} = {F}$$



## **DYNAMICS ANALYSIS (FREE VIBRATION)**

**\***The dynamics equation of the laminated structure in the absence of external load is obtained by using the most generally applicable Variational principle of the Hamilton :  $\int_{0}^{t_{1}} (T - T) dt = 0$ 

$$\delta \int_{t_1} (T - \Pi) dt = 0$$

**kinetic energy** 

**Total potential energy** 

Λ

$$T = \frac{1}{2} \int_{v} \rho \frac{\partial u_{i}}{\partial t} \frac{\partial u_{i}}{\partial t} dv \qquad \Pi = U + W$$

The general equation of motion and for non-forced system (non-damped free vibrations) is:

$$[M]{\ddot{q}}+[k]{q}=0$$



To obtain the vibratory Natural Frequencies amounts we have to solve the following Eigenvalue problem:

$$\left(\left[k\right]-\omega^{2}\left[M\right]\right)\left\{X\right\}=0$$

$$\det\left(\left\lceil k\right\rceil - \omega^2 \left\lceil M\right\rceil\right) = 0$$

 $\omega$  Is the vibration natural frequency of the plate (rd/s).

 $\{X\}$  Is the vector of global displacements (vibration modes).

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#### □ Validation Tests of R4FSDT element.

#### **Case 1 : Isotropic Square Plate**

	a/h	10	y t	
	E	10.92 MPA		
	υ	0.3		/L
	G P	4.2 MPA 1N/m <sup>2</sup>		
W,	max =	$a \cdot \frac{D}{q a^4}$	L .	h 



# **TABLE 1**: The Maximum Deflection at the Centre of SimplySupported Isotropic Square Plate

Mesh	Maximum deflection	Error (%)
(2*2)	0.09	78.64
()	0.05	
(4*4)	0.23	45.73
(6*6)	0.31	25.76
(8*8)	0.36	14.47
(10*10)	0.393	7.82
(12*12)	0.41	3.62
(14*14)	0.42	0.86
Analytical solution (Reddy)	0.42	
Numerical results (Ferreira)	0.42	



**J** Validation Tests of R4FSDT element ( Dynamics analysis )

#### **Case 1:** Isotropic simply supported square plated

**TABLE 2**: The natural frequency of a simply supported isotropic square plate

a/h	10	Mesh	Natural frequency( rd/s)	Error (%)
		(4*4)	1.34	44.62
E	10.92 MPA	(8*8)	1.03	11.72
2	0.3	(12*12)	0.97	5.24
_		(16*16)	0.95	2.94
G D	4.2 MPA $1 N / m^2$	(20*20)	0.94	1.87
F		(24*24)	0.94	1.32
$\overline{w} = w a \sqrt{\frac{\rho}{G}}$		Analytical solution (Reddy)	0.93	
		Numerical results (Ferreira)	0.93	



$$\overline{w} = wah \sqrt{\frac{\rho}{E_{22}}}$$

# Figure .12 The natural frequency of a laminated simply supported square plate (0/90/0)





Formulation

of (R4FSDT)

Validation

Tests

✓ The comparison of the numerical results obtained shows the rapid convergence of the presented element.

Conclusion

and

perspectives

#### Introduction

# As a perspective, we suggest expanding this study to:

Formulation

of (R4FSDT)

Validation

Tests

 Using a more performance element based on higher order theories of transverse shearing.
 Adopting other approaches such as the layerwise approach (layerwise theory).

> Applications of the developed element to other more complex structure .

Extend the study to the non-linear behavior of a stratified plate.

Conclusion

and

perspectives

Objective

Formulation of (R4FSDT)



Conclusion and perspectives

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